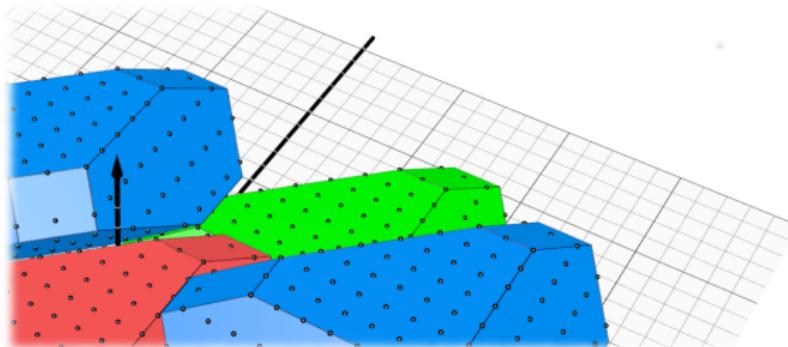


# Analyzing and Optimizing your Loops with Polly

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## **State of Variables**

### **Program**

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

### **Statement Instances Executed**

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## State of Variables

$n = 4, i = 0, j = 0$

## Statement Instances Executed

$S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## State of Variables

$n = 4, i = 1, j = 0$

## Statement Instances Executed

$S(1,0),$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

$n = 4, i = 1, j = 1$

## Statement Instances Executed

$S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## State of Variables

$n = 4, i = 2, j = 0$

## Statement Instances Executed

$S(2,0),$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## State of Variables

n = 4, i = 2, j = 1

## Statement Instances Executed

S(2,0), S(2,1),  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## State of Variables

n = 4, i = 2, j = 2

## Statement Instances Executed

S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## State of Variables

n = 4, i = 3, j = 0

## Statement Instances Executed

S(3,0),  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 3, j = 1

## Statement Instances Executed

S(3,0), S(3,1),  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 3, j = 2

## Statement Instances Executed

S(3,0), S(3,1), S(3,2),  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 3, j = 3

## Statement Instances Executed

S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 4, j = 0

## Statement Instances Executed

S(4,0),  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 4, j = 1

## Statement Instances Executed

S(4,0), S(4,1),  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 4, j = 2

## Statement Instances Executed

S(4,0), S(4,1), S(4,2),  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 4, j = 3

## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3),  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i,j);
```

## State of Variables

n = 4, i = 4, j = 4

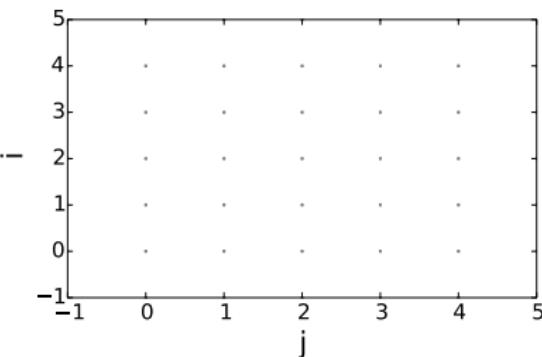
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 4$

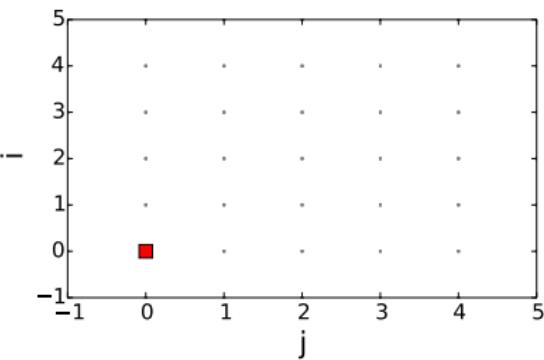
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 0, j = 0$

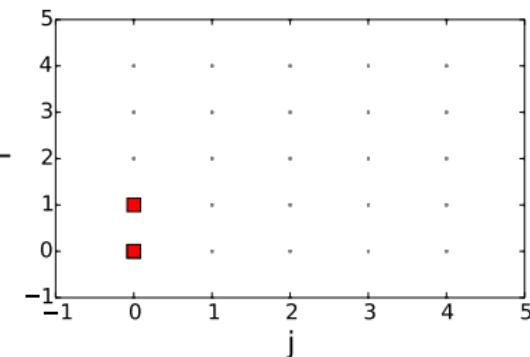
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 **$S(0,0)$**

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 1, j = 0$

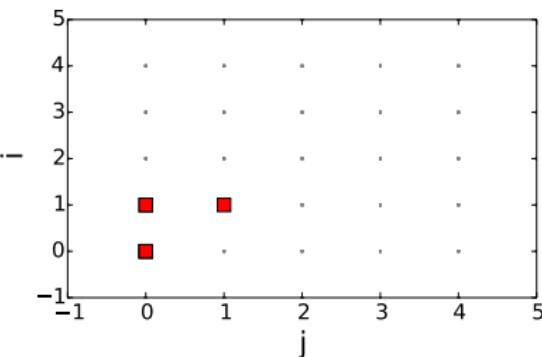
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 1, j = 1$

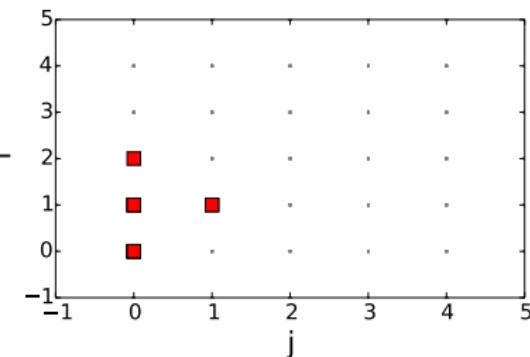
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 2, j = 0$

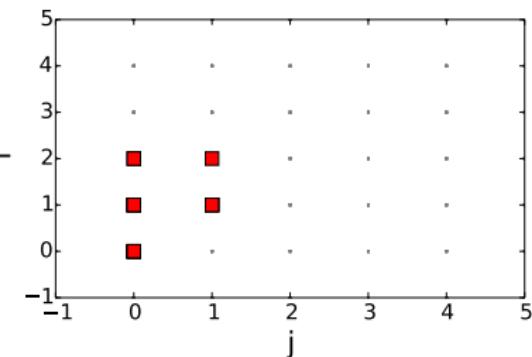
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 2, j = 1$

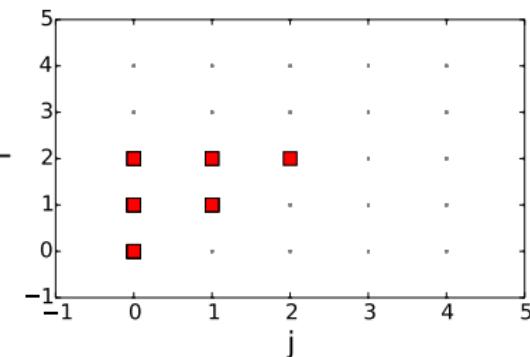
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 2, j = 2$

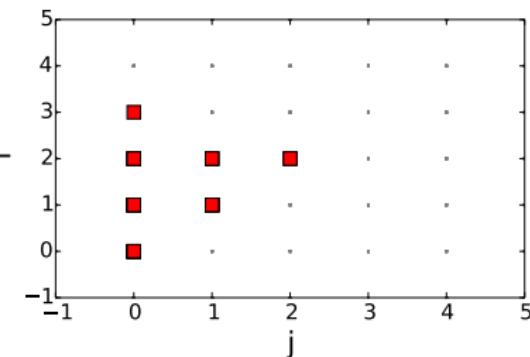
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 3, j = 0$

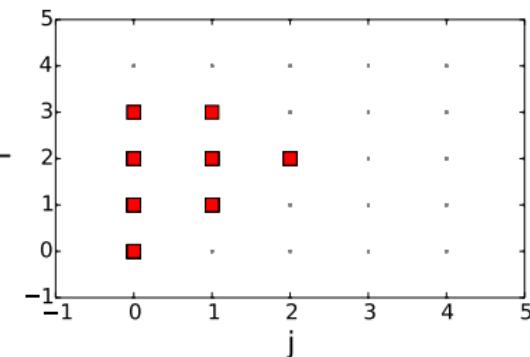
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
**S(3,0)**, S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 3, j = 1$

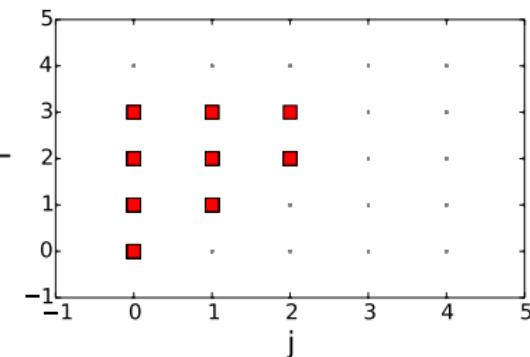
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 3, j = 2$

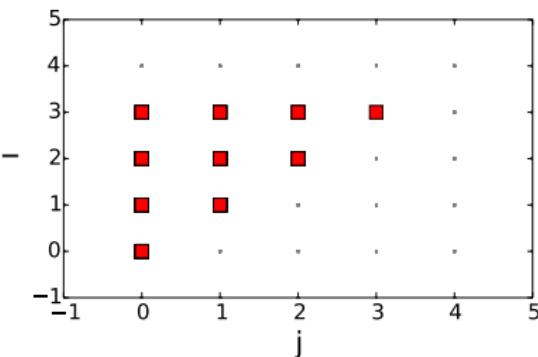
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 3, j = 3$

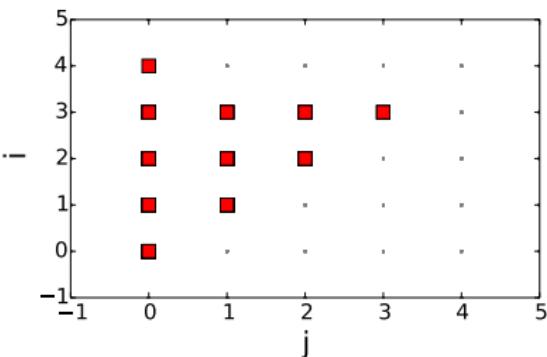
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), **S(3,3)**  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 0$

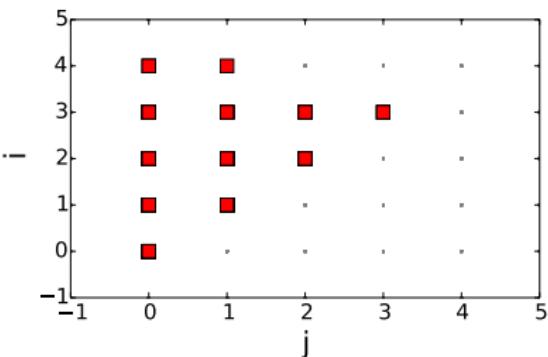
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 1$

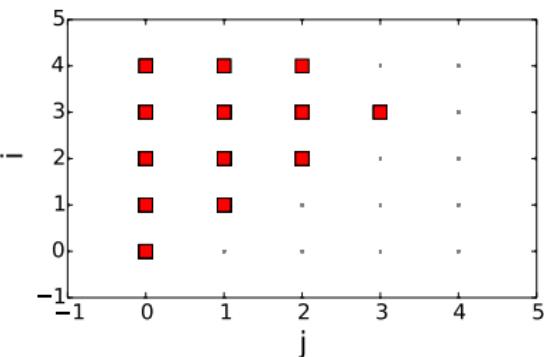
## Statement Instances Executed

$S(4,0)$ ,  $S(4,1)$ ,  $S(4,2)$ ,  $S(4,3)$ ,  $S(4,4)$   
 $S(3,0)$ ,  $S(3,1)$ ,  $S(3,2)$ ,  $S(3,3)$   
 $S(2,0)$ ,  $S(2,1)$ ,  $S(2,2)$   
 $S(1,0)$ ,  $S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 2$

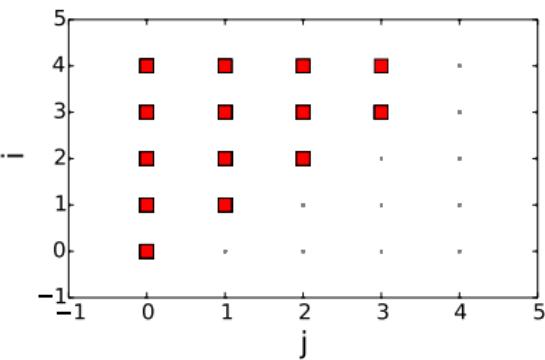
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 3$

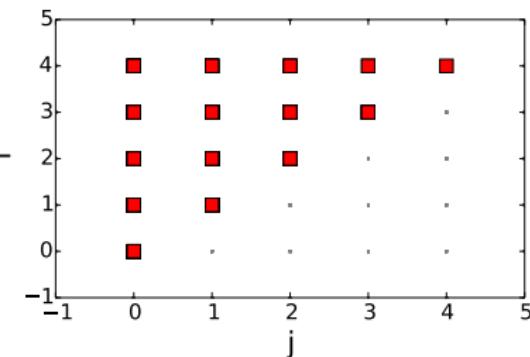
## Statement Instances Executed

S(4,0), S(4,1), S(4,2), **S(4,3)**, S(4,4)  
S(3,0), S(3,1), S(3,2), S(3,3)  
S(2,0), S(2,1), S(2,2)  
S(1,0), S(1,1)  
S(0,0)

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 4$

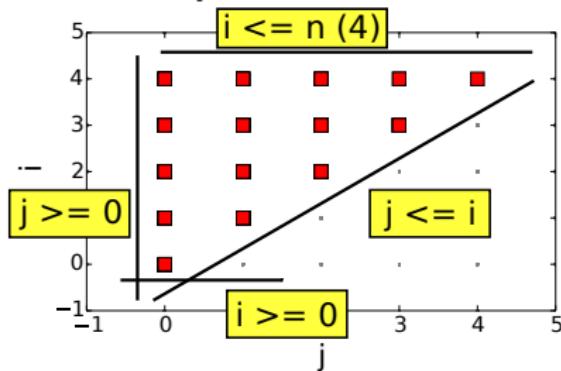
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$n = 4, i = 4, j = 4$

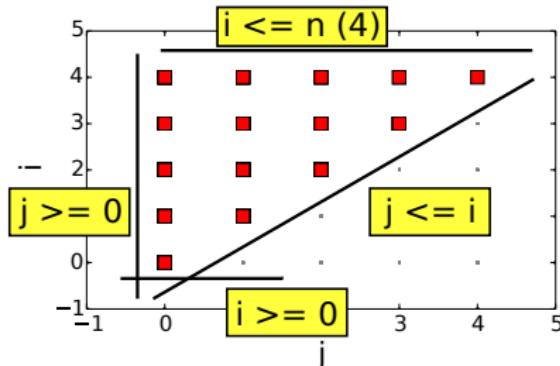
## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

## Program

```
for (i = 0; i <= n; i++)  
    for (j = 0; j <= i; j++)  
        S(i,j);
```

## Iteration space



## State of Variables

$$n = 4, i = 4, j = 4$$

## Statement Instances Executed

$S(4,0), S(4,1), S(4,2), S(4,3), S(4,4)$   
 $S(3,0), S(3,1), S(3,2), S(3,3)$   
 $S(2,0), S(2,1), S(2,2)$   
 $S(1,0), S(1,1)$   
 $S(0,0)$

$$= \{S(i,j) \mid 0 \leq i \leq n \wedge 0 \leq j \leq i\}$$

# Schedule: Original

## Model

$$\mathcal{I}_S = \{S(i, j) \mid 0 \leq i \leq n \wedge 0 \leq j \leq i\}$$

$$\Theta_S = \{S(i, j) \rightarrow (i, j)\}$$

## Code

```
for (i = 0; i <= n; i++)
    for (j = 0; j <= i; j++)
        S(i, j);
```

# Schedule: Original

## Model

$$\mathcal{I}_S = \{S(i, j) \mid 0 \leq i \leq n \wedge 0 \leq j \leq i\}$$

$$\Theta_S = \{S(i, j) \rightarrow (i, j)\}$$

## Code

```
for (c0 = 0; c0 <= n; c0++)
    for (c1 = 0; c1 <= c0; c1++)
        S(c0, c1);
```

# Schedule: Interchanged

## Model

$$\mathcal{I}_S = \{S(i, j) \mid 0 \leq i \leq n \wedge 0 \leq j \leq i\}$$

$$\Theta_S = \{S(i, j) \rightarrow (j, i)\}$$

## Code

```
for (c0 = 0; c0 <= n; c0 += 1)
    for (c1 = c0; c1 <= n; c1 += 1)
        S(c1, c0);
```

# Schedule: Strip-Mined

## Model

$$\mathcal{I}_S = \{S(i, j) \mid 0 \leq i \leq n \wedge 0 \leq j \leq i\}$$

$$\Theta_S = \{S(i, j) \rightarrow ([i/4], j, i \bmod 4)\}$$

## Code

```
for (c0 = 0; c0 <= floord(n, 4); c0 += 1)
    for (c1 = 0; c1 <= min(n, 4 * c0 + 3); c1 += 1)
        for (c2 = max(0, -4 * c0 + c1);
            c2 <= min(3, n - 4 * c0); c2 += 1)
            S(4 * c0 + c2, c1);
```

# Schedule: Tiled

## Model

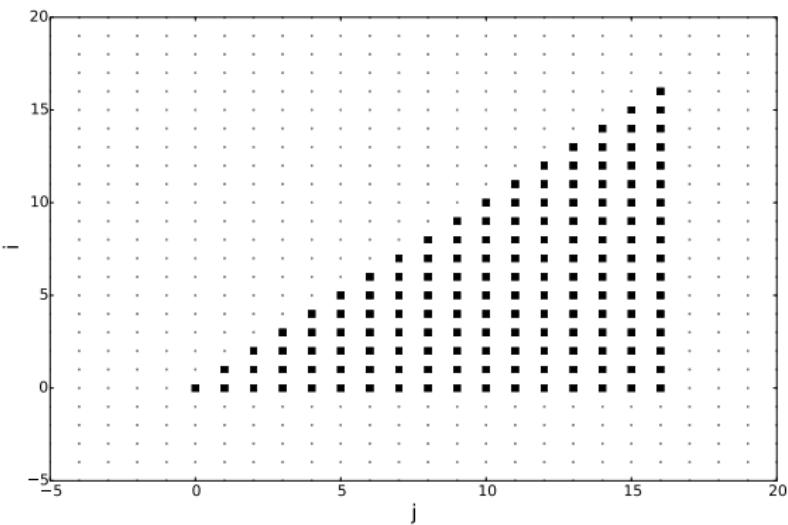
$$\mathcal{I}_S = \{S(i, j) \mid 0 \leq i \leq n \wedge 0 \leq j \leq i\}$$

$$\Theta_S = \{S(i, j) \rightarrow ([i/4], [j/4], i \bmod 4, j \bmod 4)\}$$

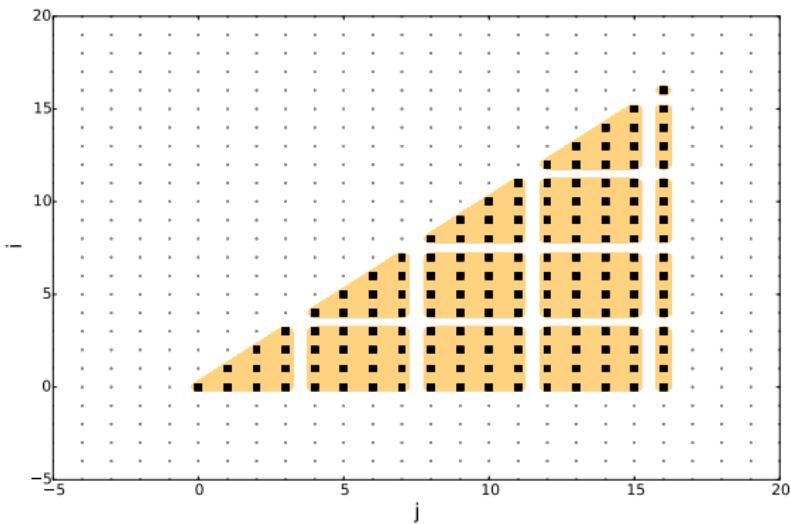
## Code

```
// Tiles
for (c0 = 0; c0 <= floord(n, 4); c0 += 1)
    for (c1 = 0; c1 <= c0; c1 += 1)
        // Iterations
        for (c2 = 0; c2 <= min(3, n - 4 * c0); c2 += 1)
            for (c3 = 0; c3 <= min(3, 4 * c0 - 4 * c1 + c2);
```

# Tiling illustrated



# Tiling illustrated



# Polly

# Get Polly

- ▶ Install Polly  
`http://polly.grosser.es/get_started.html`
- ▶ Load Polly into clang (or gcc, opt, ...)  
`alias clang clang -Xclang -load -Xclang LLVMPolly.so`
- ▶ Default behaviour preserved
- ▶ Enable Polly optionally

# Optimizing with Polly

```
for (int i = 0; i < N; i++)
    for (int j = 0; j < M; j++) {
        C[i][j] = 0;
        for (int k = 0; k < K; k++)
            C[i][j] += A[i][k] + B[k][j];
    }
```

# Optimizing with Polly

```
for (int i = 0; i < N; i++)
    for (int j = 0; j < M; j++) {
        C[i][j] = 0;
        for (int k = 0; k < K; k++)
            C[i][j] += A[i][k] + B[k][j];
    }
```

```
$ clang -O3 gemm.c -o gemm clang
$ time ./gemm clang
real 0m15.336
```

# Optimizing with Polly

```
for (int i = 0; i < N; i++)
    for (int j = 0; j < M; j++) {
        C[i][j] = 0;
        for (int k = 0; k < K; k++)
            C[i][j] += A[i][k] + B[k][j];
    }
```

```
$ clang -O3 gemm.c -o gemm clang
$ time ./gemm clang
real 0m15.336

$ clang -O3 gemm.c -o gemm.polly -mllvm -polly
$ time ./gemm.polly
real 0m2.144s
```

# LLVM's Loop Optimization Infrastructure

## Loop Analysis

- ▶ Natural Loop Detection
- ▶ Scalar Evolution
- ▶ (Region Info)

## Simple Loop Transformations

- ▶ Loop Simplify
- ▶ Loop Rotation
- ▶ Induction Variable Simplification
- ▶ Loop Invariant Code Motion
- ▶ Loop Unroll
- ▶ Loop Unswitch
- ▶ Loop Strength Reduction

## Classical Loop Transformations

- ▶ Loop Interchange (not part of -O3)
- ▶ Loop Distribution (not part of -O3)

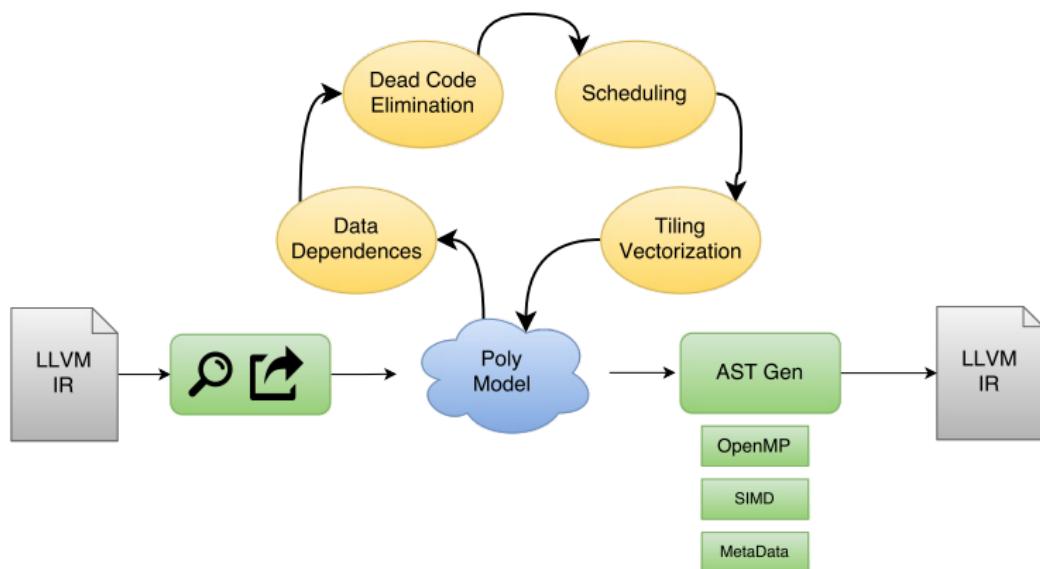
## Vectorization

- ▶ Loop Vectorization
- ▶ SLP vectorization
- ▶ BB vectorizer (outdated)

## Other

- ▶ Loop Reroll

# The Polly Architecture



## Report detected scops: -Rpass-analysis=polly

```
1 void foo(long T, float A[][] [1024]) {
2     for (long t = 0; t < T; t++)
3         for (long i = 1; i < 1024 - 1; i++)
4             A[t+1][i] += A[t][i+1] + A[t][i-1];
5 }
```

```
$ polly-clang-opt -O3 -mllvm -polly -Rpass-analysis=polly scop.c
scop.c:2:3: remark: SCoP begins here. [-Rpass-analysis=polly-scops]
    for (long t = 0; t < T; t++)
^
scop.c:4:50: remark: SCoP ends here. [-Rpass-analysis=polly-scops]
        A[t+1][i] += A[t][i+1] + A[t][i-1];
```

## Report problems: -Rpass-missed=polly

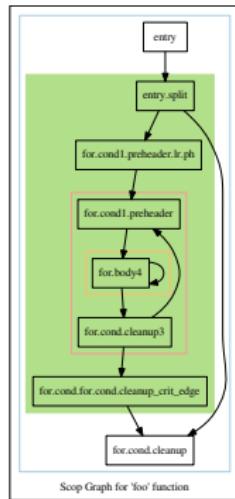
```
1 float sideeffect(float);
2 void foo(long T, long N, float A[][][N]) {
3     for (long t = 0; t < T; t++)
4         for (long i = 1; i < N - 1; i++)
5             A[t+1][i] += sideeffect(A[t][i+1] + A[t][i-1]);
6 }
```

```
$polly-clang-opt -c -O3 -mllvm -polly -Rpass-missed=polly missed.c
missed.c:3:5: remark: The following errors keep this region
                  from being a Scop.
                  [-Rpass-missed=polly-detect]
for (long i = 1; i < N - 1; i++)
^

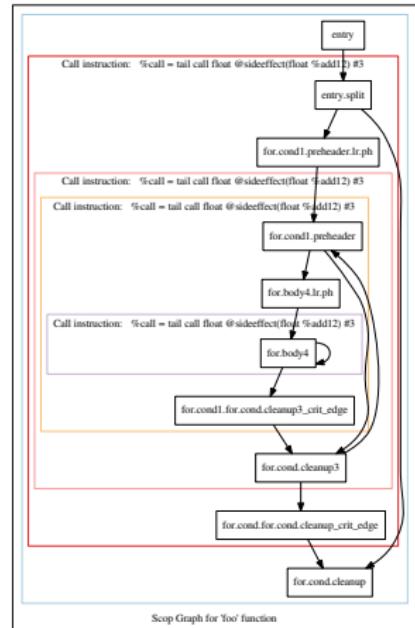
missed.c:5:20: remark: This function call cannot be handled.
                  Try to inline it.
                  [-Rpass-missed=polly-detect]
A[t+1][i] += sideeffect(A[t][i+1] + A[t][i-1]);
```

# Highlight SCoPs in CFG

-polly-show



-polly-view-all



# The Polyhedral Representation (-debug-only=polly-scops)

```
for (long t = 0; t < T; t++)
    for (long i = 1; i < 1024 - 1; i++)
        A[t+1][i] += A[t][i+1] + A[t][i-1];
```

```
Domain :=
[T] -> { Stmt_for_body4[i0, i1] : 0 <= i0 < T and 0 <= i1 <= 1021 };

Schedule :=
[T] -> { Stmt_for_body4[i0, i1] -> [i0, i1] };

ReadAccess := [Reduction Type: NONE] [Scalar: 0]
[T] -> { Stmt_for_body4[i0, i1] -> MemRef_A[i0, 2 + i1] };

ReadAccess := [Reduction Type: NONE] [Scalar: 0]
[T] -> { Stmt_for_body4[i0, i1] -> MemRef_A[i0, i1] };

ReadAccess := [Reduction Type: NONE] [Scalar: 0]
[T] -> { Stmt_for_body4[i0, i1] -> MemRef_A[1 + i0, 1 + i1] };

MustWriteAccess := [Reduction Type: NONE] [Scalar: 0]
[T] -> { Stmt_for_body4[i0, i1] -> MemRef_A[1 + i0, 1 + i1] };
```

## The Generated AST: (-debug-only=polly-ast)

```
for (long t = 0; t < T; t++)
    for (long i = 1; i < 1024 - 1; i++)
        A[t+1][i] += A[t][i+1] + A[t][i-1];
```



```
if (1)
    for (c0 = 0; c0 < T; c0+=1)
        for (c1 = c0; c1 <= c0+1021; c1+=1)
            Stmt_for_body4(c0, -c0 + c1);
else
{ /* original code */ }
```

# Supported constructs

# Supported constructs

## Loops

- ▶ counted

```
for (i=0; i < n / 13; i+=2)
```

# Supported constructs

## Loops

- ▶ counted
  - `for (i=0; i < n / 13; i+=2)`
- ▶ Presburger Expressions
  - `for (i=0; i<22 && i>n; i+=2)`

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- ▶ Multiple back-edges/exit-edges
  - `break; continue;`

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- ▶ Presburger Conditions
  - `if (5*i+b <= 13 12 > b)`

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`for (i=0; i < n / 13; i+=2)`
- ▶ Presburger Expressions  
`for (i=0; i<22 && i>n; i+=2)`
- ▶ Multiple back-edges/exit-edges  
`break; continue;`
- ▶ do..while, while

## Conditions

- ▶ Presburger Conditions  
`if (5*i+b <= 13 12 > b)`
- ▶ Data-dependent  
`if (B[i]) A[i] = A[i]/B[i]`

# Supported constructs

## Loops

- ▶ counted  
`for (i=0; i < n / 13; i+=2)`
- ▶ Presburger Expressions  
`for (i=0; i<22 && i>n; i+=2)`
- ▶ Multiple back-edges/exit-edges  
`break; continue;`
- ▶ `do..while, while`

## Conditions

- ▶ Presburger Conditions  
`if (5*i+b <= 13 12 > b)`
- ▶ Data-dependent  
`if (B[i]) A[i] = A[i]/B[i]`
- ▶ Unstructured control flow  
`goto;`

# Supported constructs

## Loops

- ▶ counted  
`for (i=0; i < n / 13; i+=2)`
- ▶ Presburger Expressions  
`for (i=0; i<22 && i>n; i+=2)`
- ▶ Multiple back-edges/exit-edges  
`break; continue;`
- ▶ `do..while, while`

## Conditions

- ▶ Presburger Conditions  
`if (5*i+b <= 13 12 > b)`
- ▶ Data-dependent  
`if (B[i]) A[i] = A[i]/B[i]`
- ▶ Unstructured control flow  
`goto;`

## Arrays

- ▶ Multi-dimensionality: `A [] [n] [m] / A [] [10] [100]`
- ▶ Keywords: `restrict`

## Calls

- ▶ Memory intrinsics: `memset/memmove/memcpy`
- ▶ Approximated behaviour:  
`read-none/read-only(pointer-arguments-only)`

# Examples: Valid SCoPs

## do..while loop

```
int i = 0;  
  
do {  
    int b = 2 * i;  
    int c = b * 3 + 5 * i;  
    A[c] = i;  
    i++;  
} while (i < N);
```

## pointer loop

```
int A[1024]  
int *B;  
  
while(B < &A[1024]) {  
    *B = i;  
    ++B;  
}
```

# Profitability Heuristics

## Polly's default policy: No regressions

- ▶ Minimal compile time increase
- ▶ No spurious run-time changes

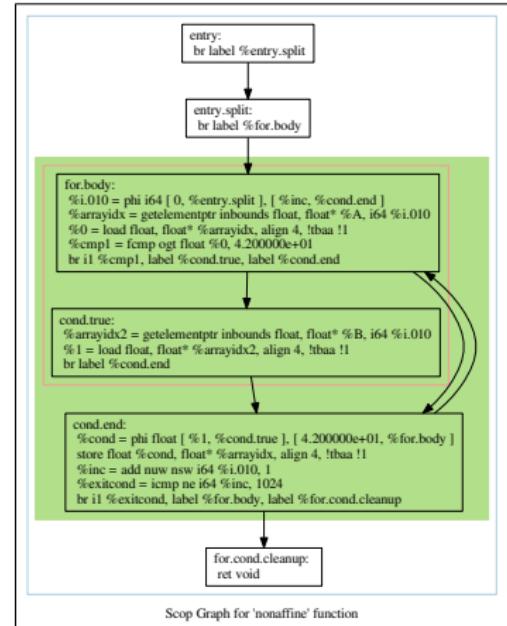
## Rules:

- ▶ Bail out as early as possible
  - ▶ At least two loops (or one very big one)
  - ▶ At least one read access
- ▶ Only change IR if Polly did something beneficial
  - ▶ Performed Schedule Transformation
  - ▶ Added alias run-time check

Can be overwritten by: `-polly-process-unprofitable`

# Non-affine Statements

```
void nonaffine(float A[],  
              float B[]) {  
    for (long i = 0; i < 1024; i++)  
        A[i] = A[i] > 42 ? B[i] : 42;  
}
```



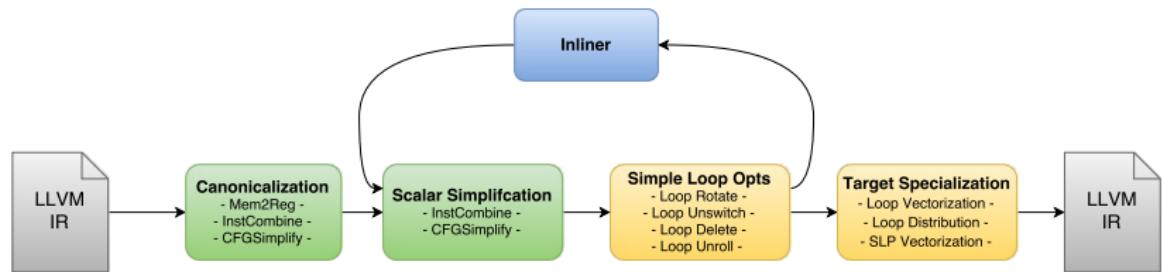
# Schedule Optimizer: -polly-opt-isl

Roman Garev (outer-loop vectorization)

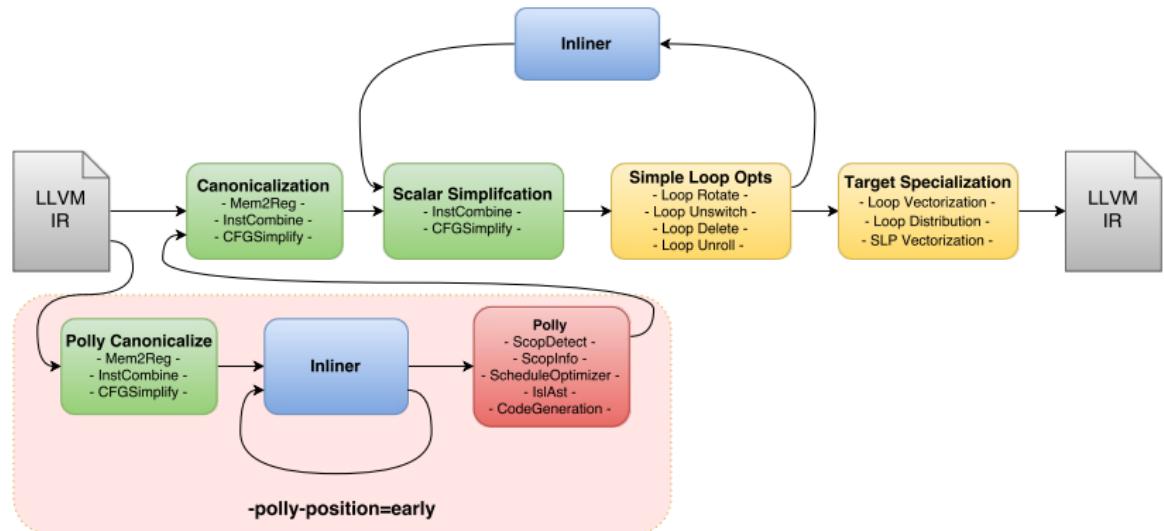
- ▶ Schedule using a Pluto style LP to maximize:
  - ▶ Data locality
  - ▶ Parallelism
  - ▶ Tilability
- ▶ Post-scheduling optimizations
  - ▶ Tile innermost tileable band
  - ▶ Strip-mine innermost parallel loop for SIMDization

**Implementation:** isl\_schedule

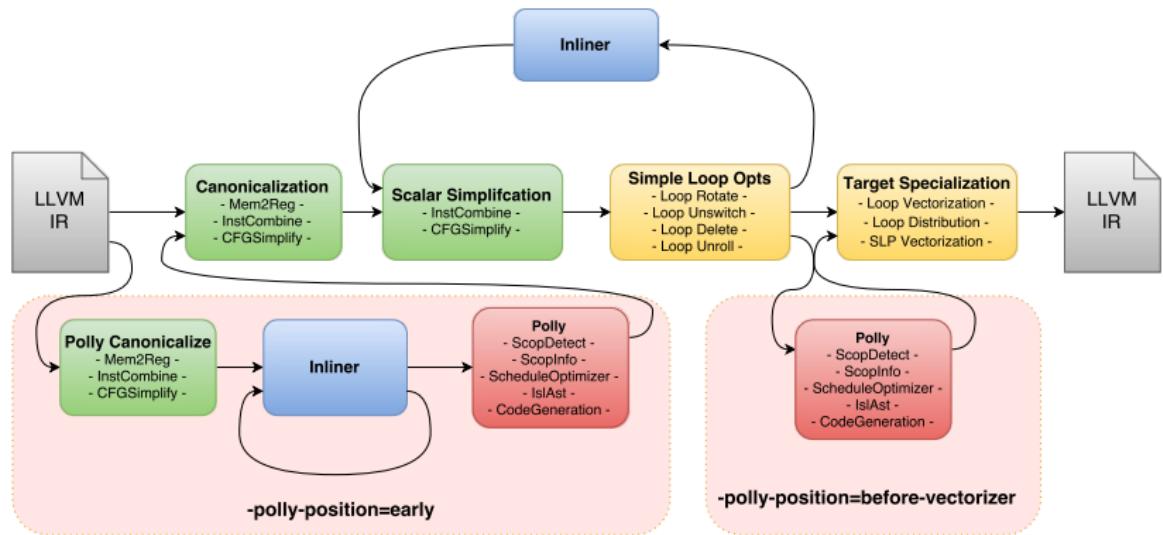
# LLVM Pass Pipeline



# LLVM Pass Pipeline



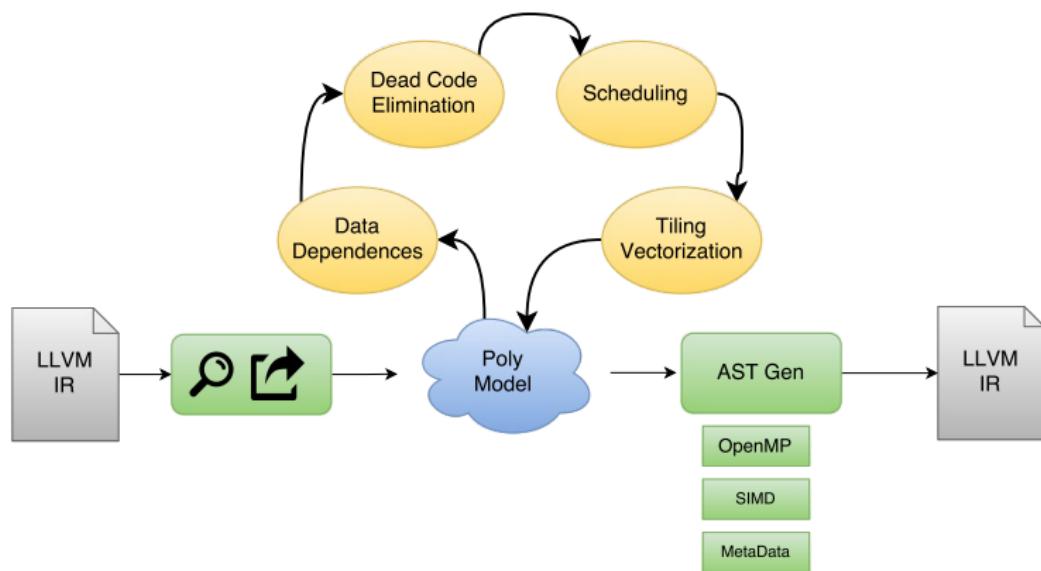
# LLVM Pass Pipeline



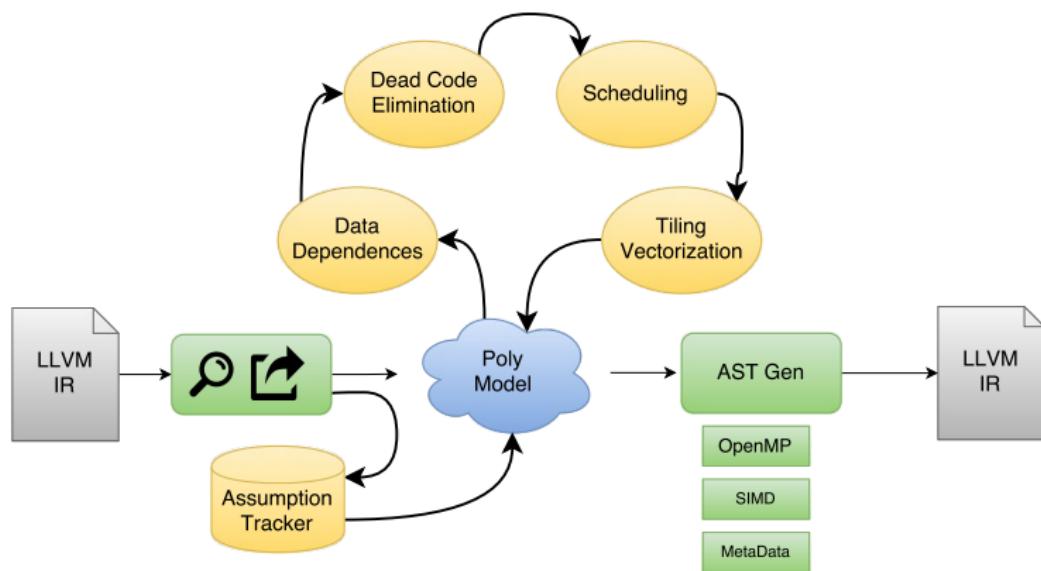
## Auto Parallelization: (-mllvm) -polly-parallel (-lgomp)

- ▶ Run outer-most parallel loop with OpenMP
- ▶ Directly emit calls to libgomp (gcc's OpenMP library)
- ▶ Execution can be controlled by setting OMP environment variables:
  - ▶ `OMP_SCHEDULE=static,dynamic,guided,auto`
  - ▶ `OMP_NUM_THREADS=< num >` or `(-mllvm)`  
`-polly-num-threads=< num >`

# Optimistic Assumption Tracking



# Optimistic Assumption Tracking



## Assumption tracking in Polly

```
1 void oddEvenCopy(int N, int M, float A[] [M]) {  
2     for (int i = 0; i < M; i++)  
3         for (int j = 0; j < N; j++)  
4             A[2 * j][i] = A[2 * j + 1][i];  
5 }
```

⇒ 15s

## Assumption tracking in Polly

```
1 void oddEvenCopy(int N, int M, float A[] [M]) {  
2     for (int i = 0; i < M; i++)  
3         for (int j = 0; j < N; j++)  
4             A[2 * j][i] = A[2 * j + 1][i];  
5 }
```

⇒ 15s

↓ Clearly beneficial loop interchange ↓

```
1 void oddEvenCopy(int N, int M, float A[] [M]) {  
2     for (int j = 0; j < N; j++)  
3         for (int i = 0; i < M; i++)  
4             A[2 * j][i] = A[2 * j + 1][i];  
5 }
```

⇒ 2s

... is not always obvious to the compiler

```
1 void oddEvenCopy(int N, int M, float A[] [20000]) {  
2     for (int i = 0; i < M; i++)  
3         for (int j = 0; j < N; j++)  
4             A[2 * j][i] = A[2 * j + 1][i];  
5 }
```

⇒ ?

... is not always obvious to the compiler

```
1 void oddEvenCopy(int N, int M, float A[] [20000]) {  
2     for (int i = 0; i < M; i++)  
3         for (int j = 0; j < N; j++)  
4             A[2 * j][i] = A[2 * j + 1][i];  
5 }
```

⇒ ?

- ▶ Interchange only allowed if  $M \leq 20000$  (or  $N < 0$ )
- ▶ ..., but code with  $M = 20001$  is well defined.

## Be optimistic - Optimize for the common case

1. Take & collect assumptions
2. Simplify
3. Verify dynamically

## Run-time alias checks

```
void aliasChecks(long n, long m,
                 float A[],
                 float B[][] [m]) {
    for (long i = 0; i < n; i++)
        for (long j = 0; j < m; j++)
            A[i] += B[i][j];
}
```

# Run-time alias checks

```
void aliasChecks(long n, long m,
                 float A[],
                 float B[][] m) {
    for (long i = 0; i < n; i++)
        for (long j = 0; j < m; j++)
            A[i] += B[i][j];
} →
if (&B[n-1][m] <= &A[0]
    || &A[n] <= &B[0][0])
    for (int c0 = 0; c0 < n; c0 += 1)
        for (int c1 = 0; c1 < m; c1 += 1)
            Stmt_for_body4(c0, c1);
else
{ /* original code */ }
```

# Possibly Invariant Loads

```
void mayLoad(int *s0, int *s1) {  
    for (int i = 0; i < *s0; i++)  
        for (int j = 0; j < *s1; j++)  
            ...  
}
```

# Possibly Invariant Loads

```
void mayLoad(int *s0, int *s1) {  
    for (int i = 0; i < *s0; i++)  
        for (int j = 0; j < *s1; j++)  
            ...  
}
```



```
void mayLoad(int *s0, int *s1) {  
    int s0val = *s0;  
    int s1val = 1;  
  
    if (s0val > 0)  
        s1val = *s1;  
  
    for (int i = 0; i < s0val; i++)  
        for (int j = 0; j < s1val; j++)  
            ...  
}
```

# Check Hoisting

```
for (int i = 0; i < N; i++) {
    for (int j = 0; j < N; j++)
        A[i][j] = B[i][j];

    if (DebugLevel > 5)
        printf("Column %d copied\n", i)
}
```

# Check Hoisting

```
for (int i = 0; i < N; i++) {  
    for (int j = 0; j < N; j++)  
        A[i][j] = B[i][j];  
  
    if (DebugLevel > 5)  
        printf("Column %d copied\n", i)  
}
```



```
if (DebugLevel <= 5) {  
  
    #pragma parallel  
    for (int i = 0; i < N; i++)  
        #pragma simd  
        for (int j = 0; j < N; j++)  
            A[i][j] = B[i][j];  
  
} else {  
    /* .. */  
}
```

## User provided assumptions

```
void user(long n, long m,
          float A[][][1024],
          float B[][][1024]) {
    for (long i = 0; i < n; i++)
        for (long j = 0; j < m; j++)
            A[i][j] += B[i][j];
}
```

# User provided assumptions

```
void user(long n, long m,
          float A[][][1024],
          float B[][][1024]) {
    for (long i = 0; i < n; i++)
        for (long j = 0; j < m; j++)
            A[i][j] += B[i][j];
}
```



```
if (m <= 1024)
    for (int c0 = 0; c0 < n; c0 += 1)
        for (int c1 = 0; c1 < m; c1 += 1)
            Stmt_for_body4(c0, c1);
else
    { /* original code */ }
```

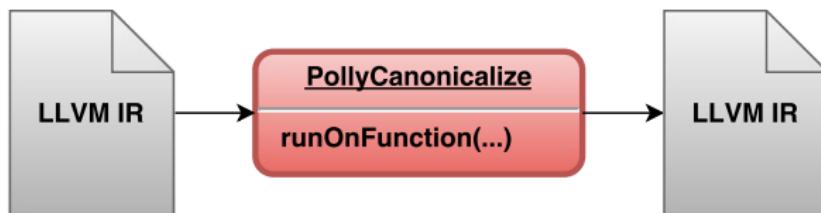
## User provided assumptions II

```
void user(long n, long m,
          float A[] [1024],
          float B[] [1024]) {
    __builtin_assume(m <= 1024);
    for (long i = 0; i < n; i++)
        for (long j = 0; j < m; j++)
            A[i][j] += B[i][j];
}
```

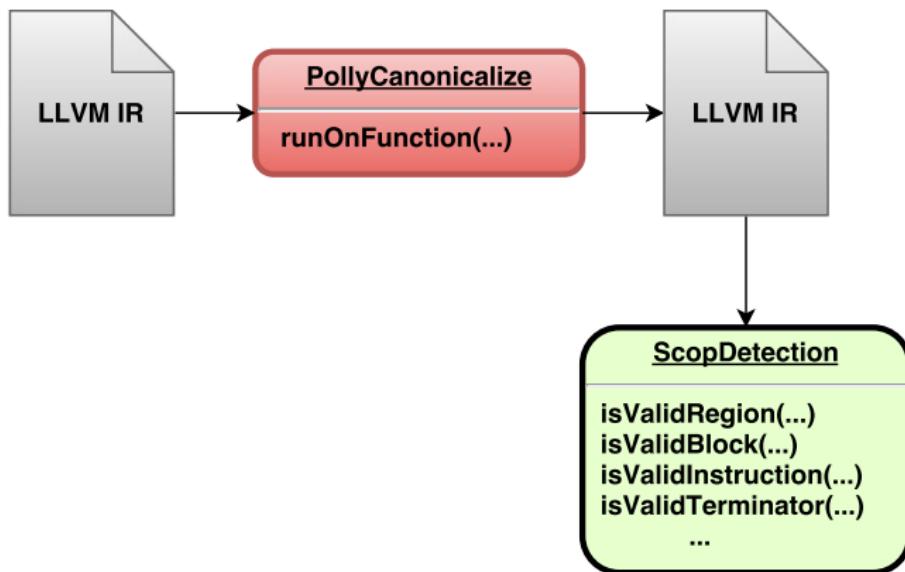


```
if (1)
    for (int c0 = 0; c0 < n; c0 += 1)
        for (int c1 = 0; c1 < m; c1 += 1)
            Stmt_for_body4(c0, c1);
else
    { /* original code */ }
```

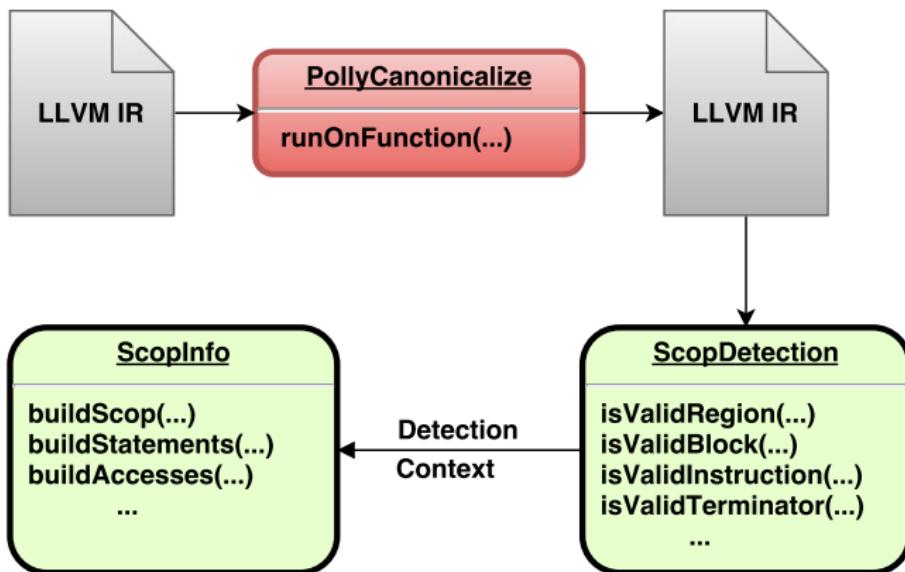
# Polly Implementation



# Polly Implementation



# Polly Implementation



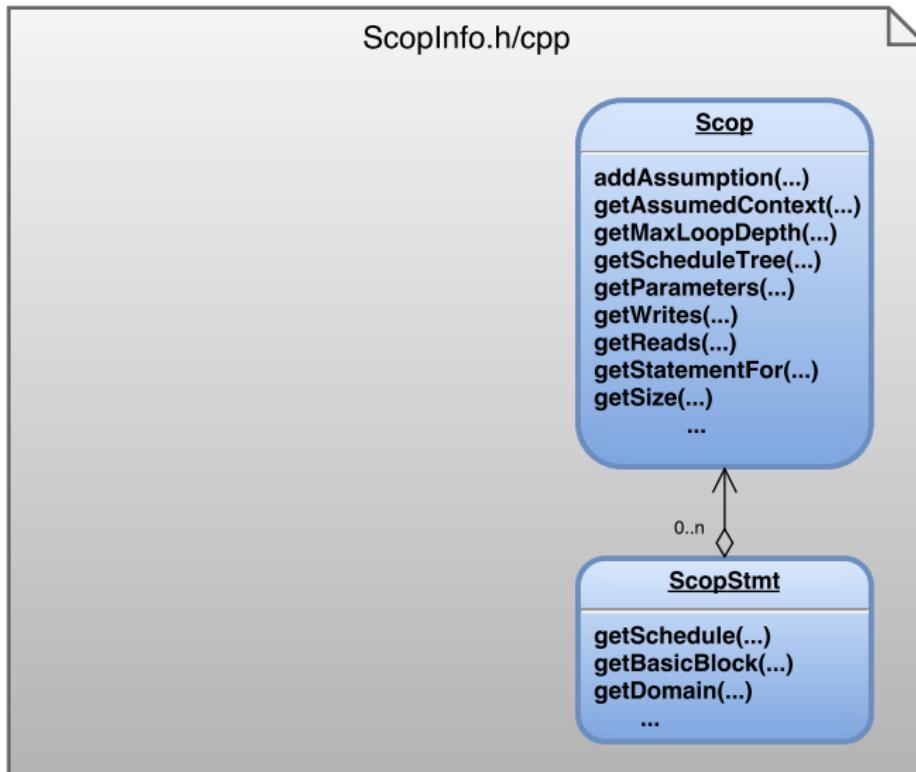
# SCoP Representation

ScopInfo.h/cpp

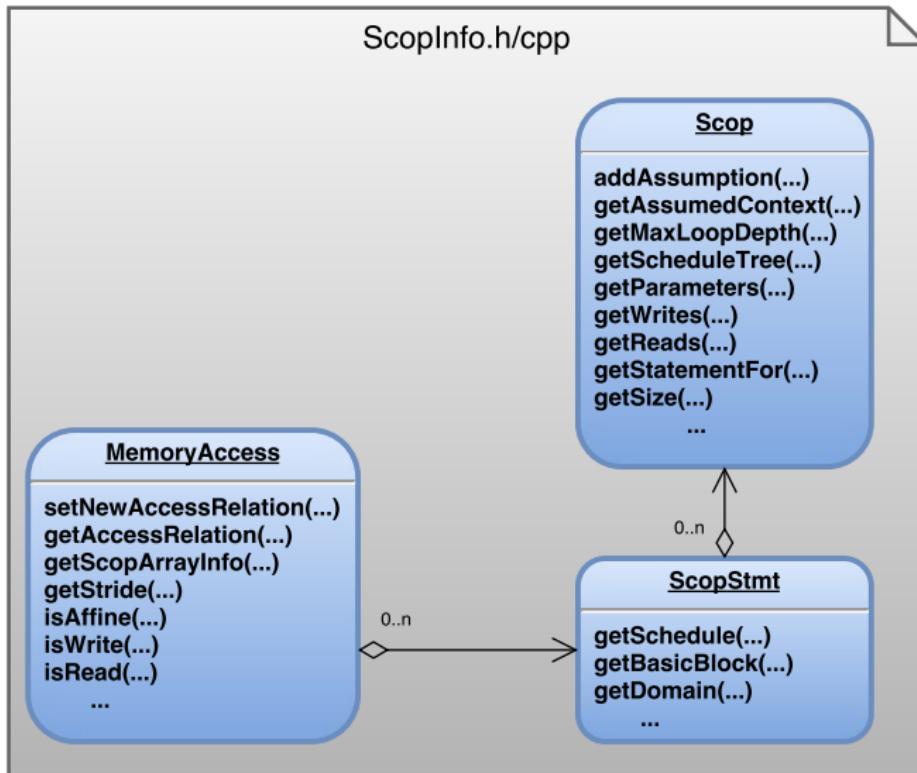
## Scop

```
addAssumption(...)  
getAssumedContext(...)  
getMaxLoopDepth(...)  
getScheduleTree(...)  
getParameters(...)  
getWrites(...)  
getReads(...)  
getStatementFor(...)  
getSize(...)  
...
```

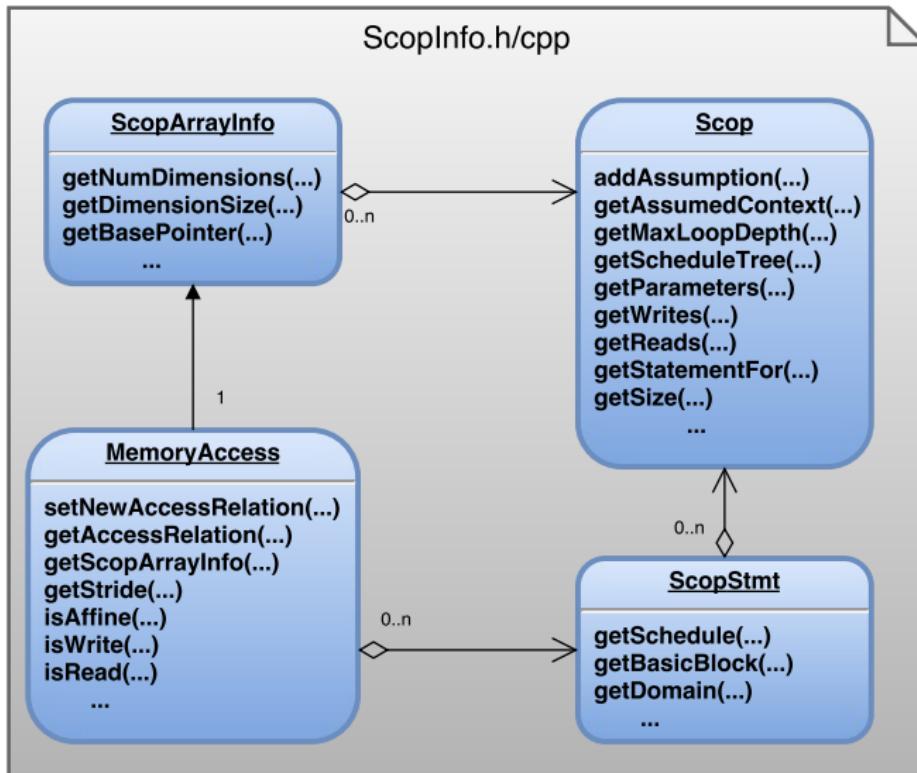
# SCoP Representation



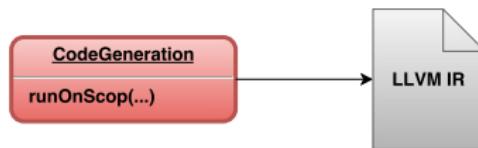
# SCoP Representation



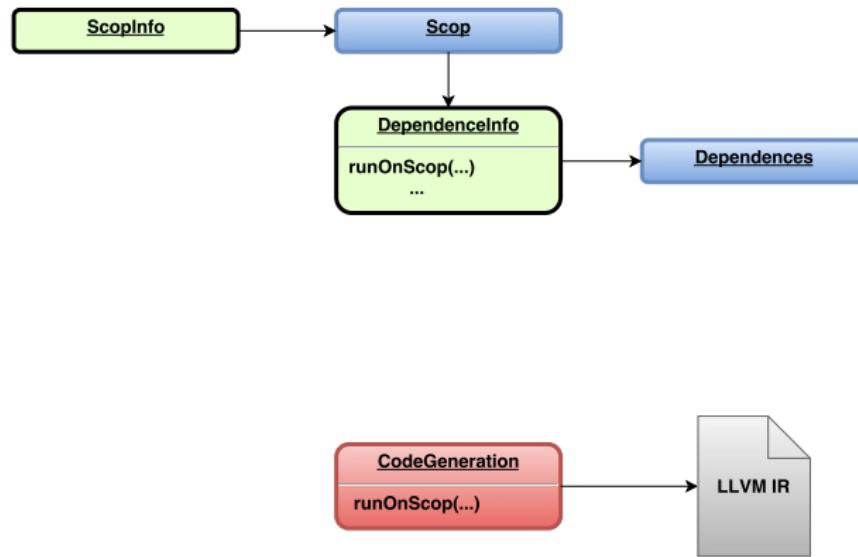
# SCoP Representation



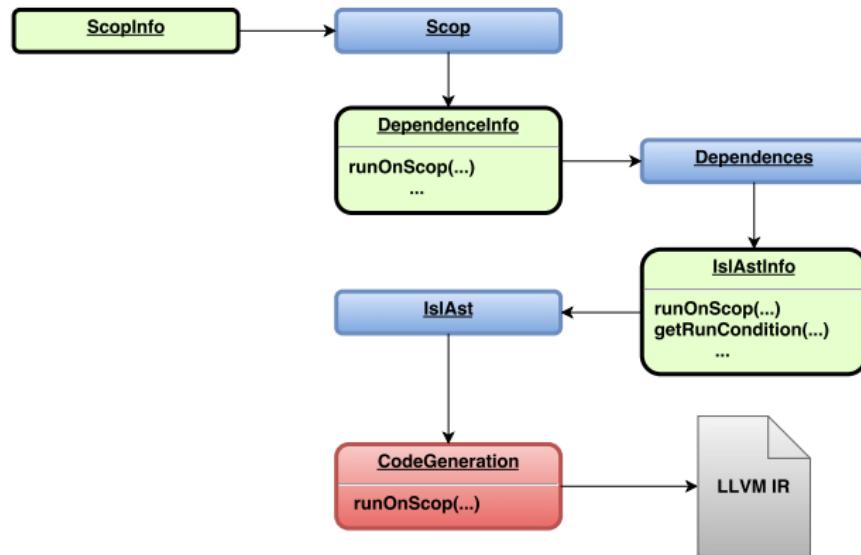
# Polly Implementation



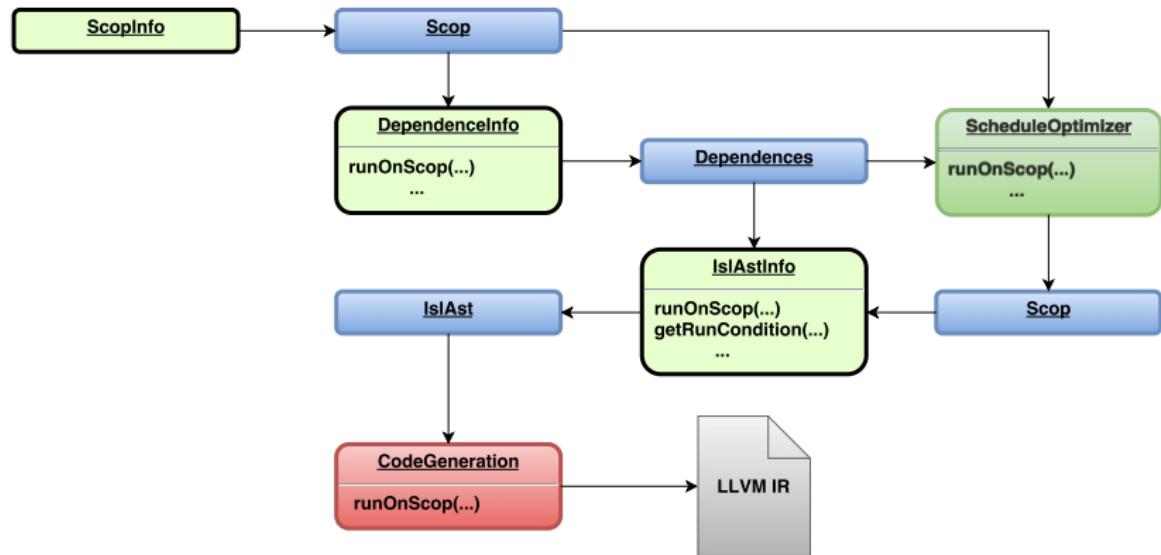
# Polly Implementation



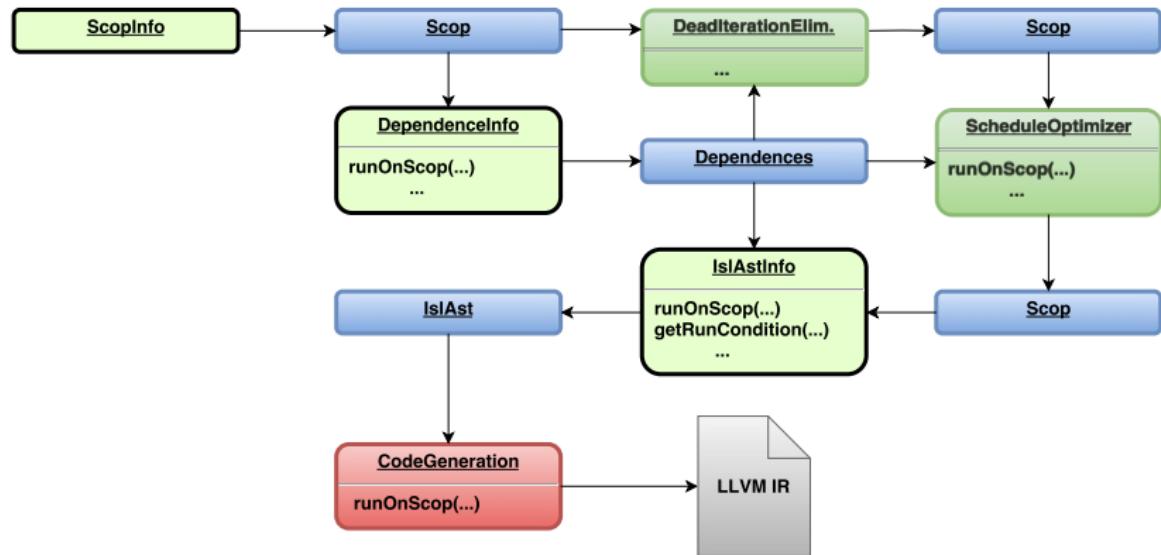
# Polly Implementation



# Polly Implementation



# Polly Implementation



# NAS Parallel Benchmarks — BT — rhs.c

# NAS Parallel Benchmarks — BT — rhs.c

```
void compute_rhs() {
    int i, j, k, m;
    double rho_inv, uijk, up1, um1, vijk, vp1, vm1, wijk, wp1, wm1;

    if (timeron) timer_start(t_rhs);

    for (k = 0; k <= grid_points[2]-1; k++) {
        for (j = 0; j <= grid_points[1]-1; j++) {
            for (i = 0; i <= grid_points[0]-1; i++) {
                rho_inv = 1.0/u[k][j][i][0];
                rho_i[k][j][i] = rho_inv;
                us[k][j][i] = u[k][j][i][1] * rho_inv;
                vs[k][j][i] = u[k][j][i][2] * rho_inv;
                ws[k][j][i] = u[k][j][i][3] * rho_inv;
                square[k][j][i] = 0.5*(
                    u[k][j][i][1]*u[k][j][i][1] +
                    u[k][j][i][2]*u[k][j][i][2] +
                    u[k][j][i][3]*u[k][j][i][3] ) * rho_inv;
                qs[k][j][i] = square[k][j][i] * rho_inv;
            }
        }
    }
}
```

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++) {
    for (j = 0; j <= grid_points[1]-1; j++) {
        for (i = 0; i <= grid_points[0]-1; i++) {
            for (m = 0; m < 5; m++) {
                rhs[k][j][i][m] = forcing[k][j][i][m];
            }
        }
    }
}

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
            uijk = us[k][j][i];
            up1 = us[k][j][i+1];
            um1 = us[k][j][i-1];

            rhs[k][j][i][0] = rhs[k][j][i][0] + dx1tx1 *
                (u[k][j][i+1][0] - 2.0*u[k][j][i][0] +
                 u[k][j][i-1][0]) -
                tx2 * (u[k][j][i+1][1] - u[k][j][i-1][1]);
        }
    }
}
```

# NAS Parallel Benchmarks — BT — rhs.c

```
rhs[k][j][i][1] = rhs[k][j][i][1] + dx2tx1 *
    (u[k][j][i+1][1] - 2.0*u[k][j][i][1] +
     u[k][j][i-1][1]) +
    xxcon2*con43 * (up1 - 2.0*uijk + um1) -
    tx2 * (u[k][j][i+1][1]*up1 -
            u[k][j][i-1][1]*um1 +
            (u[k][j][i+1][4] - square[k][j][i+1]-
             u[k][j][i-1][4] + square[k][j][i-1])* c2);

rhs[k][j][i][2] = rhs[k][j][i][2] + dx3tx1 *
    (u[k][j][i+1][2] - 2.0*u[k][j][i][2] +
     u[k][j][i-1][2]) +
    xxcon2 * (vs[k][j][i+1] - 2.0*vs[k][j][i] +
               vs[k][j][i-1]) -
    tx2 * (u[k][j][i+1][2]*up1 - u[k][j][i-1][2]*um1);

rhs[k][j][i][3] = rhs[k][j][i][3] + dx4tx1 *
    (u[k][j][i+1][3] - 2.0*u[k][j][i][3] +
     u[k][j][i-1][3]) +
    xxcon2 * (ws[k][j][i+1] - 2.0*ws[k][j][i] +
               ws[k][j][i-1]) -
    tx2 * (u[k][j][i+1][3]*up1 - u[k][j][i-1][3]*um1);

/* ≈300 more lines of similar code */
```

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++)
    for (j = 0; j <= grid_points[1]-1; j++)
        for (i = 0; i <= grid_points[0]-1; i++)
            for (m = 0; m < 5; m++)
                rhs[k][j][i][m] = forcing[k][j][i][m];

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
/* ... */
```

---

<sup>a</sup>Sanyam and Yew, PLDI 15

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++)
    for (j = 0; j <= grid_points[1]-1; j++)
        for (i = 0; i <= grid_points[0]-1; i++)
            for (m = 0; m < 5; m++)
                rhs[k][j][i][m] = forcing[k][j][i][m];

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
            /* ... */
```

+ 6× speedup for 8 threads/cores <sup>a</sup>

---

<sup>a</sup>Sanyam and Yew, PLDI 15

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++)
    for (j = 0; j <= grid_points[1]-1; j++)
        for (i = 0; i <= grid_points[0]-1; i++)
            for (m = 0; m < 5; m++)
                rhs[k][j][i][m] = forcing[k][j][i][m];

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
            /* ... */
```

- + 6× speedup for 8 threads/cores <sup>a</sup>
- Possible variant loop bounds

---

<sup>a</sup>Sanyam and Yew, PLDI 15

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++)
    for (j = 0; j <= grid_points[1]-1; j++)
        for (i = 0; i <= grid_points[0]-1; i++)
            for (m = 0; m < 5; m++)
                rhs[k][j][i][m] = forcing[k][j][i][m];

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
            /* ... */
```

- + 6× speedup for 8 threads/cores <sup>a</sup>
- Possible variant loop bounds
- Possible out-of-bound accesses

---

<sup>a</sup>Sanyam and Yew, PLDI 15

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++)
    for (j = 0; j <= grid_points[1]-1; j++)
        for (i = 0; i <= grid_points[0]-1; i++)
            for (m = 0; m < 5; m++)
                rhs[k][j][i][m] = forcing[k][j][i][m];

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
            /* ... */
```

- + 6× speedup for 8 threads/cores <sup>a</sup>
- Possible variant loop bounds
- Possible out-of-bound accesses
- Possible execution of non-pure calls

---

<sup>a</sup>Sanyam and Yew, PLDI 15

# NAS Parallel Benchmarks — BT — rhs.c

```
for (k = 0; k <= grid_points[2]-1; k++)
    for (j = 0; j <= grid_points[1]-1; j++)
        for (i = 0; i <= grid_points[0]-1; i++)
            for (m = 0; m < 5; m++)
                rhs[k][j][i][m] = forcing[k][j][i][m];

if (timeron) timer_start(t_rhsx);

for (k = 1; k <= grid_points[2]-2; k++) {
    for (j = 1; j <= grid_points[1]-2; j++) {
        for (i = 1; i <= grid_points[0]-2; i++) {
            /* ... */
```

- + 6× speedup for 8 threads/cores <sup>a</sup>
  - Possible variant loop bounds
  - Possible out-of-bound accesses
  - Possible execution of non-pure calls
  - Possible integer under/overflows complicate loop bounds

---

<sup>a</sup>Sanyam and Yew, PLDI 15

## NAS Parallel Benchmarks — BT — rhs.c

```
clang -Rpass-analysis=polly-scops -O3 -polly rhs.c
```

```
rhs.c:47:3: remark: SCoP begins here. [-Rpass-analysis=polly-scops]
```

```
for (k = 0; k <= grid_points[2]-1; k++) {
```

```
^
```

```
/* ... */
```

```
rhs.c:418:16: remark: SCoP ends here. [-Rpass-analysis=polly-scops]
```

```
if (timeron) timer_stop(t_rhs);
```

```
^
```

## NAS Parallel Benchmarks — BT — rhs.c

```
clang -Rpass-analysis=polly-scops -O3 -polly rhs.c
```

```
rhs.c:79:16: remark: No-error assumption: [grid_points, grid_points', t
      { : timeron = 0 } [-Rpass-analysis=polly-scops]
if (timeron) timer_start(t_rhsx);
^
```

# NAS Parallel Benchmarks — BT — rhs.c

```
clang -Rpass-analysis=polly-scops -O3 -polly rhs.c
```

```
rhs.c:50:23: remark: Inbounds assumption: [grid_points, grid_points', grid_points''] ->
{ : grid_points <= 0 or (grid_points >= 1 and grid_points' <= 0) or (grid_points >= 1 and
    grid_points' >= 104 and grid_points'' <= 0) or (grid_points >= 1 and grid_points' <= 103
        and grid_points' >= 1 and grid_points'' <= 103) } [-Rpass-analysis=polly-scops]
    rho_inv = 1.0/u[k][j][i][0];
    ^

rhs.c:144:27: remark: Inbounds assumption: [grid_points, grid_points', timeron, grid_points''] ->
{ : grid_points <= 2 or (grid_points >= 3 and grid_points' <= 104) } [-Rpass-analysis=polly-scops]
    rhs[k][j][i][m] = rhs[k][j][i][m] - dssp *
    ^

rhs.c:171:27: remark: Inbounds assumption: [grid_points, grid_points', timeron, grid_points''] ->
{ : grid_points <= 2 or (grid_points >= 3 and grid_points' <= 2) or (grid_points >= 3
    and grid_points' <= 104 and grid_points' >= 3 and grid_points'' <= 105 and grid_points'' >= 3) }
    rhs[k][j][i][m] = rhs[k][j][i][m] - dssp *
    ^
```

# NAS Parallel Benchmarks — BT — rhs.c

```
clang -Rpass-analysis=polly-scops -O3 -polly rhs.c
```

```
rhs.c:419:1: remark: No-overflows assumption: [grid_points, grid_points'', timeron] ->
{: (grid_points >= 3 and grid_points' >= 3 and grid_points'' >= -2147483643) or (grid_points >= 3 and
grid_points' <= 2 and grid_points' >= -2147483643 and grid_points'' >= -2147483646) or
(grid_points <= 2 and grid_points >= -2147483643 and grid_points' >= 3 and grid_points'' >= -2147483646)
(grid_points <= 2 and grid_points >= -2147483644 and grid_points' <= 2 and grid_points' >= -2147483646)
(grid_points' = -2147483644 and grid_points >= 3 and grid_points'' <= 2 and grid_points'' >= -2147483646)
(grid_points = -2147483644 and grid_points' >= 3 and grid_points'' <= 2 and grid_points'' >= -2147483646)
```

```
__builtin_assume(grid_points[0] >= -2147483643 &&
                  grid_points[1] >= -2147483643 &&
                  grid_points[2] >= -2147483643);
```

## NAS Parallel Benchmarks — BT — rhs.c

```
clang -Rpass-analysis=polly-scops -O3 -polly rhs.c
```

```
rhs.c:50:23: remark: Possibly aliasing pointer, use restrict keyword.  
[-Rpass-analysis=polly-scops]  
    rho_inv = 1.0/u[k][j][i][0];  
           ^  
  
rhs.c:56:13: remark: Possibly aliasing pointer, use restrict keyword.  
[-Rpass-analysis=polly-scops]  
    u[k][j][i][1]*u[k][j][i][1] +  
           ^
```

# PARSEC — blackscholes — blackscholes.c

# PARSEC — blackscholes — blackscholes.c

```
float BlkSchlsEqEuroNoDiv(float sptprice, float strike, float rate,
                           float volatility, float time, int otype) {
    float xD1, xD2, xDen, d1, d2, FutureValueX, NofXd1, NofXd2, NegNofXd1,
          NegNofXd2, Price;
    xD1 = rate + volatility * volatility; * 0.5;
    xD1 = xD1 * time;
    xD1 = xD1 + log( sptprice / strike );
    xDen = volatility * sqrt(time);
    xD1 = xD1 / xDen;
    xD2 = xD1 - xDen;
    d1 = xD1;
    d2 = xD2;
    NofXd1 = CNDF( d1 );
    NofXd2 = CNDF( d2 );
    FutureValueX = strike * ( exp( -(rate)*(time) ) );
    if (otype == 0) {
        Price = (sptprice * NofXd1) - (FutureValueX * NofXd2);
    } else {
        NegNofXd1 = (1.0 - NofXd1);
        NegNofXd2 = (1.0 - NofXd2);
        Price = (FutureValueX * NegNofXd2) - (sptprice * NegNofXd1);
    }
    return Price;
}
```

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], otime[i],
                                              return 0;
}
```

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], ottime[i],
                                              return 0;
}
```

+ 2.9× speedup for manual parallelization on a quad-core i7

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], ottime[i],
                                              return 0;
}
```

- + 2.9× speedup for manual parallelization on a quad-core i7
- + 2.8× speedup for automatic parallelization on a quad-core i7

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], ottime[i],
                                              return 0;
}
```

- + 2.9× speedup for manual parallelization on a quad-core i7
- + 2.8× speedup for automatic parallelization on a quad-core i7
- Possible aliasing

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], ottime[i],
                                              return 0;
}
```

- + 2.9× speedup for manual parallelization on a quad-core i7
- + 2.8× speedup for automatic parallelization on a quad-core i7

- Possible aliasing
- Possible execution of non-pure calls

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], otime[i],
                                              r);
    return 0;
}
```

- + 2.9× speedup for manual parallelization on a quad-core i7
- + 2.8× speedup for automatic parallelization on a quad-core i7
  
- Possible aliasing
- Possible execution of non-pure calls
- Possible execution of dead-iterations ( $0 \leq j < \text{NUM\_RUNS} - 1$ )

## PARSEC — blackscholes — blackscholes.c

```
int bs_thread(void *tid_ptr) {
    int tid = *(int *)tid_ptr;
    int start = tid * (numOptions / nThreads);
    int end = start + (numOptions / nThreads);

    for (int j = 0; j < NUM_RUNS; j++)
        for (int i = start; i < end; i++)
            prices[i] = BlkSchlsEqEuroNoDiv(sptprice[i], strike[i],
                                              volatility[i], otime[i],
                                              r);
    return 0;
}
```

- + 2.9× speedup for manual parallelization on a quad-core i7
- + 2.8× speedup for automatic parallelization on a quad-core i7
- + 6.5× speedup for sequential execution (native input)
- Possible aliasing
- Possible execution of non-pure calls
- Possible execution of dead-iterations ( $0 \leq j < \text{NUM\_RUNS} - 1$ )

# The Polly Loop Optimizer

- ▶ High-level loop manipulation framework for LLVM
  - ▶ Generic loop modeling based on “Semantic SCoPs”
  - ▶ Optimistic assumptions in case of insufficient static knowledge
  - ▶ Fast compile-time
- 
- ▶ Open and welcoming community (we try at least)
  - ▶ Industry/Research Partnership through pollylabs.org

Thank you!

## SPEC 2006 — hmmer — fast\_algorithms.c

# SPEC 2006 — hmmer — fast\_algorithms.c

```
for (k = 1; k <= M; k++) {
    mc[k] = mpp[k - 1] + tpmm[k - 1];
    if ((sc = ip[k - 1] + tpmi[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = dpp[k - 1] + tpdm[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = xmb + bp[k]) > mc[k]) mc[k] = sc;
    mc[k] += ms[k];
    if (mc[k] < -INFTY) mc[k] = -INFTY;

    dc[k] = dc[k - 1] + tpdd[k - 1];
    if ((sc = mc[k - 1] + tpmd[k - 1]) > dc[k]) dc[k] = sc;
    if (dc[k] < -INFTY) dc[k] = -INFTY;

    if (k < M) {
        ic[k] = mpp[k] + tpmi[k];
        if ((sc = ip[k] + tpii[k]) > ic[k]) ic[k] = sc;
        ic[k] += is[k];
        if (ic[k] < -INFTY) ic[k] = -INFTY;
    }
}
```

# SPEC 2006 — hmmer — fast\_algorithms.c

```
#pragma clang loop vectorize(enable)
for (k = 1; k <= M; k++) {
    mc[k] = mpp[k - 1] + tpmm[k - 1];
    if ((sc = ip[k - 1] + tpmi[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = dpp[k - 1] + tpdm[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = xmb + bp[k]) > mc[k]) mc[k] = sc;
    mc[k] += ms[k];
    if (mc[k] < -INFTY) mc[k] = -INFTY;
}
for (k = 1; k <= M; k++) {
    dc[k] = dc[k - 1] + tpdd[k - 1];
    if ((sc = mc[k - 1] + tpmd[k - 1]) > dc[k]) dc[k] = sc;
    if (dc[k] < -INFTY) dc[k] = -INFTY;

    if (k < M) {
        ic[k] = mpp[k] + tpmi[k];
        if ((sc = ip[k] + tpii[k]) > ic[k]) ic[k] = sc;
        ic[k] += is[k];
        if (ic[k] < -INFTY) ic[k] = -INFTY;
    }
}
```

+

up to 30% speedup

# SPEC 2006 — hmmer — fast\_algorithms.c

```
for (k = 1; k <= M; k++) {
    mc[k] = mpp[k - 1] + tpmm[k - 1];
    if ((sc = ip[k - 1] + tpmi[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = dpp[k - 1] + tpdm[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = xmb + bp[k]) > mc[k]) mc[k] = sc;
    mc[k] += ms[k];
    if (mc[k] < -INFTY) mc[k] = -INFTY;

    dc[k] = dc[k - 1] + tpdd[k - 1];
    if ((sc = mc[k - 1] + tpmd[k - 1]) > dc[k]) dc[k] = sc;
    if (dc[k] < -INFTY) dc[k] = -INFTY;
}

#pragma clang loop vectorize(enable)
for (k = 1; k <= M; k++) {
    if (k < M) {
        ic[k] = mpp[k] + tpmi[k];
        if ((sc = ip[k] + tpii[k]) > ic[k]) ic[k] = sc;
        ic[k] += is[k];
        if (ic[k] < -INFTY) ic[k] = -INFTY;
    }
}
```

+

up to 30% speedup

# SPEC 2006 — hmmer — fast\_algorithms.c

```
#pragma clang loop vectorize(enable)
for (k = 1; k <= M; k++) {
    mc[k] = mpp[k - 1] + tpmm[k - 1];
    if ((sc = ip[k - 1] + tpmi[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = dpp[k - 1] + tpdm[k - 1]) > mc[k]) mc[k] = sc;
    if ((sc = xmb + bp[k]) > mc[k]) mc[k] = sc;
    mc[k] += ms[k];
    if (mc[k] < -INFTY) mc[k] = -INFTY;
}
for (k = 1; k <= M; k++) {
    dc[k] = dc[k - 1] + tpdd[k - 1];
    if ((sc = mc[k - 1] + tpmd[k - 1]) > dc[k]) dc[k] = sc;
    if (dc[k] < -INFTY) dc[k] = -INFTY;
}
#pragma clang loop vectorize(enable)
for (k = 1; k <= M; k++) {
    if (k < M) {
        ic[k] = mpp[k] + tpmi[k];
        if ((sc = ip[k] + tpii[k]) > ic[k]) ic[k] = sc;
        ic[k] += is[k];
        if (ic[k] < -INFTY) ic[k] = -INFTY;
    }
}
```

+

up to 50% speedup

## SPEC 2006 — hmmer — fast\_algorithms.c

## SPEC 2006 — hmmer — fast\_algorithms.c

1 vectorized loop       $\Rightarrow$       + up to 30% speedup

## SPEC 2006 — hmmer — fast\_algorithms.c

- 1 vectorized loop       $\Rightarrow$       + up to 30% speedup
- 2 vectorized loops       $\Rightarrow$       + up to 50% speedup

## SPEC 2006 — hmmer — fast\_algorithms.c

- 1 vectorized loop       $\Rightarrow$       + up to 30% speedup
- 2 vectorized loops       $\Rightarrow$       + up to 50% speedup
- possible aliasing       $\Rightarrow$       - runtime alias checks

## SPEC 2006 — hmmer — fast\_algorithms.c

- 1 vectorized loop       $\Rightarrow$       + up to 30% speedup
- 2 vectorized loops       $\Rightarrow$       + up to 50% speedup
- possible aliasing       $\Rightarrow$       - runtime alias checks
- possible dependences     $\Rightarrow$       - static dependence analysis